

How to Answer a Question.?!

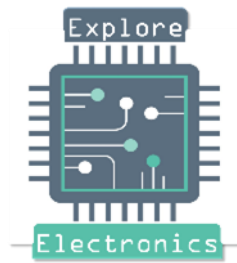
What Would be the Expected Answer.?!

How to get Maximum marks in VTU Valuation.?!



Solution to Model Question Paper 1

Basic Electronics & Communication Engineering



Model

Question Paper-1

SOLUTION

[Solution Explanation Video : https://youtu.be/t_w_2wjmBKQ](https://youtu.be/t_w_2wjmBKQ)

Q.01 a With neat block diagram explain the working of a DC power supply. Also mention the principal components used in each block.

7

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Diagram 2+2=4M

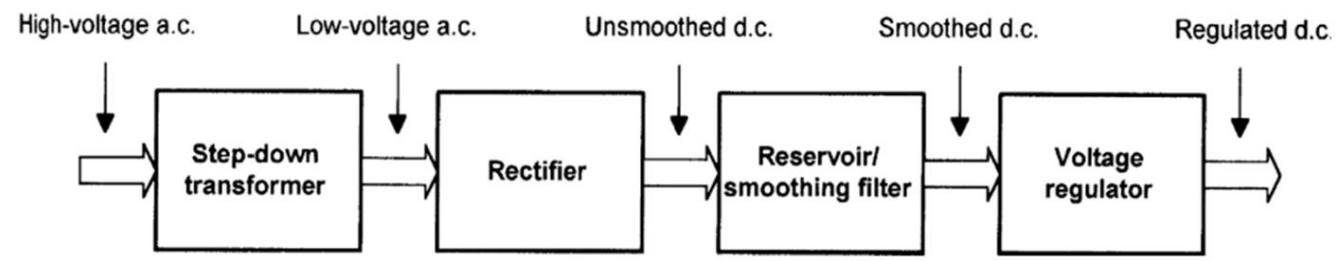


Figure 6.1 Block diagram of a d.c. power supply

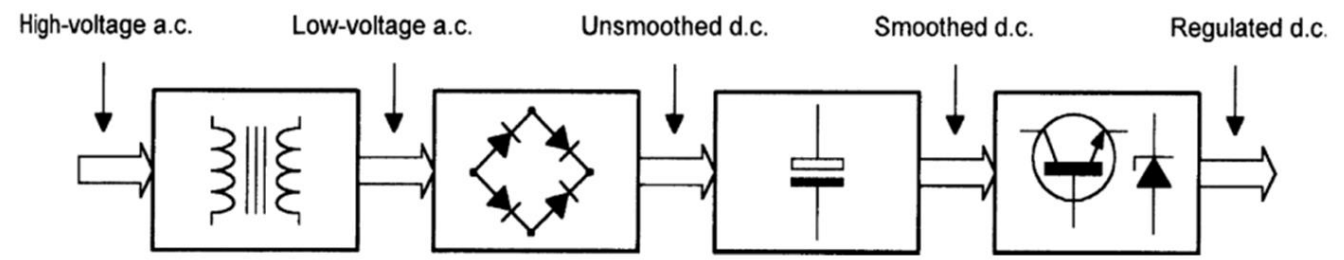
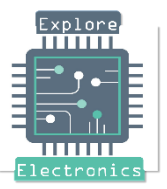


Figure 6.2 Block diagram of a d.c. power supply showing principal components

Explanation 3M

Write two to three lines of Explanation for these points

- Step down transformer reduces the AC voltage to low voltage
- Rectifier is a circuit which converts a.c signal into pulsating d.c signal
- Reservoir/smoothing circuit reduces ripples/pulses present in rectifier output
- Voltage regulator make the dc output voltage constant even in small variation in input



b) Mention advantages of negative feedback in amplifiers circuits. With relevant equations and diagram explain the concept of negative feedback.

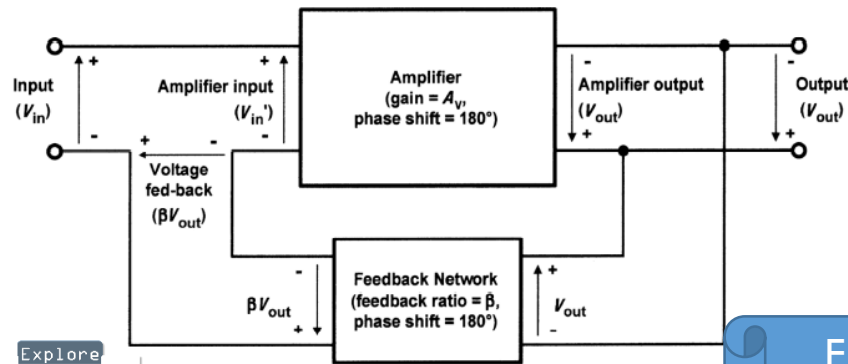
Advantages of Negative Feedback

Advantages 3M

- Stabilizes Amplifier Gain.
- Reduces Non-linear Distortion.
- Increases Circuit Stability.
- Increases Input Impedance/Resistance.
- Decreases Output Impedance/Resistance.
- Reduces Noise Level.
- Improves Frequency Response & Bandwidth.

Equations & Explanation 2M

Diagram 2M



$$\text{Overall Gain } G = \frac{V_o}{V_s} \dots\dots\dots(1)$$

$$\text{Amplifier Gain } A = \frac{V_o}{V_i}$$
$$V_o = AV_i \dots\dots\dots(2)$$

$$V_s = V_i + \beta V_o \dots\dots\dots(3)$$

Explain Phase shift in three to four lines of explanation

$$\text{Overall Gain } G = \frac{A}{1 + A\beta}$$

c With circuit diagram and waveform show how operational amplifier can work as a comparator.

6

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Diagram 2M

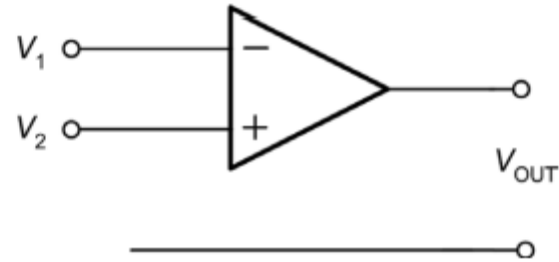


Figure 8.17 A comparator

Waveform & Explanation

4M

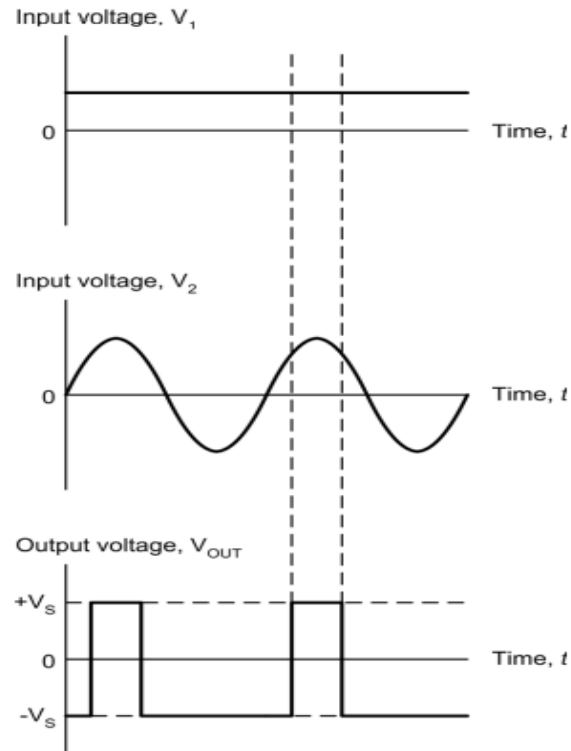
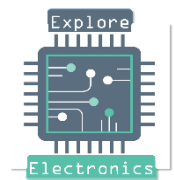
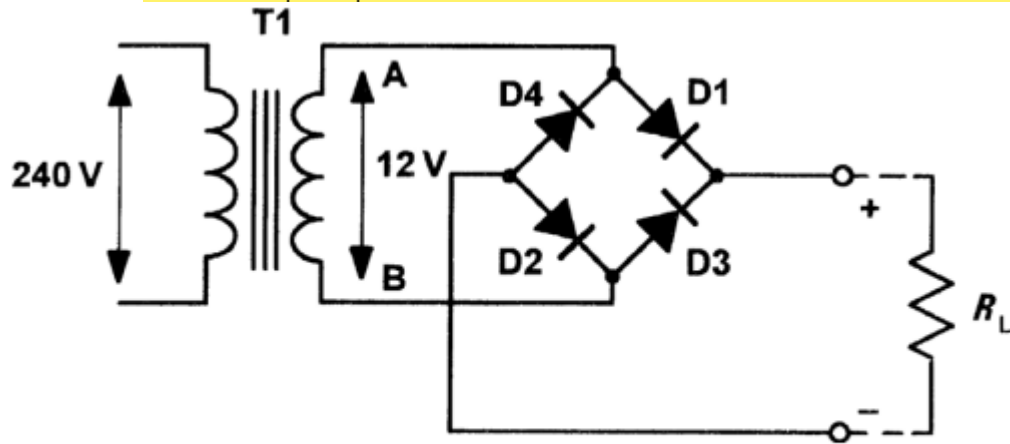


Figure 8.18 Typical input and output waveforms for a comparator





2M

- On positive half-cycles,
- point A will be positive with respect to point B.
- In this condition D1 and D2 will allow conduction
- while D3 and D4 will not allow conduction.

Waveform &
Explanation

4M

- Conversely, on negative half-cycles, point B will be positive with respect to point A.
- In this condition D3 and D4 will allow conduction while D1 and D2 will not allow conduction.

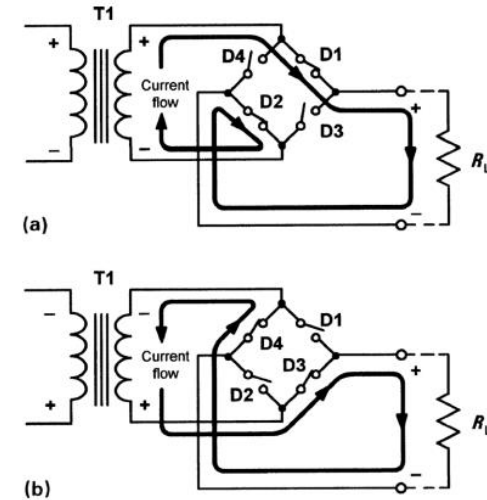


Figure 6.16 (a) Bridge rectifier with D1 and D2 conducting, D3 and D4 non-conducting (b) bridge rectifier with D1 and D2 non-conducting, D3 and D4 conducting

Diagram

2M

b Write a note on frequency response characteristics of an amplifier circuit, clearly mentioning the half power frequencies.

6

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Waveform 2M

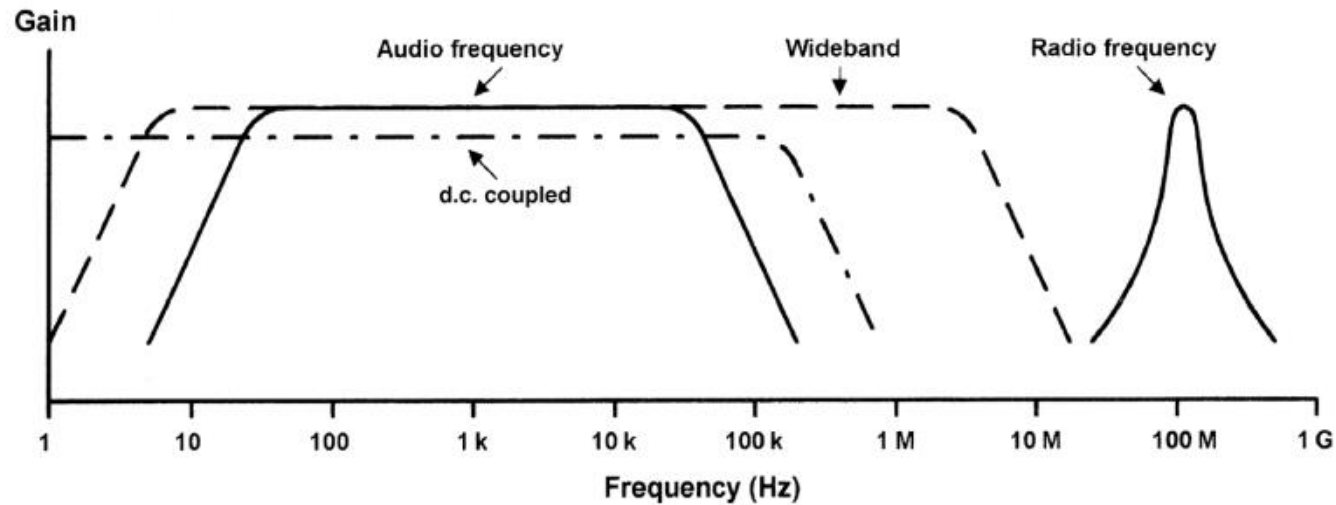


Figure 7.9 Frequency response and bandwidth (output power plotted against frequency)

These frequencies are those at which the output power has dropped to 50% (otherwise known as the **-3 dB points**) or where the voltage gain has dropped to 70.7% of its mid-band value.

Explanation 2M

Waveform 2M

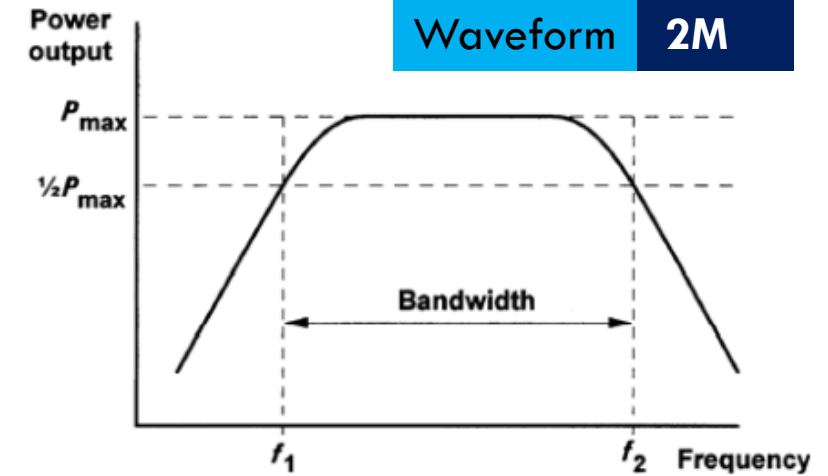
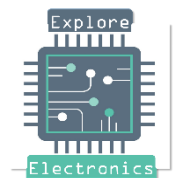


Figure 7.10 Frequency response and bandwidth (output power plotted against frequency)



c List and explain conditions for sustained oscillations. Determine the frequency of oscillation of a three-stage ladder network in which $C=10 \text{ nF}$ and $R=10 \text{ k}\Omega$.

6

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1. The feedback must be positive

(The signal fed back must arrive back in-phase with the signal at the input).

Phase Shift of Amplifier and feedback network should be **0 or 360** degree

2 conditions

2M

2. The overall loop voltage gain must be equal to 1

(The amplifier's gain must be sufficient to overcome the losses associated with any frequency selective feedback network). **$|A.\beta|=1$**

Problem 16

Determine the frequency of oscillation of a three stage ladder network oscillator in which $C = 10 \text{ nF}$ and $R = 10 \text{ k}\Omega$.

The frequency of oscillation of the circuit is

$$f = \frac{1}{2\pi\sqrt{6}RC} = \frac{1}{2 \times 3.14 \times \sqrt{6} \times 10 \times 10^3 \times 10 \times 10^{-9}}$$

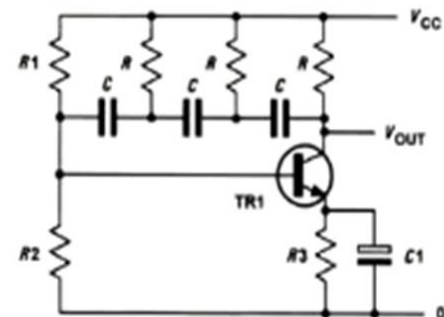
$$f = \underline{\underline{647 \text{ Hz}}}$$

Expression

1M

$$f = \frac{1}{2\pi\sqrt{2n}RC}$$

RC phase shift osc/tn



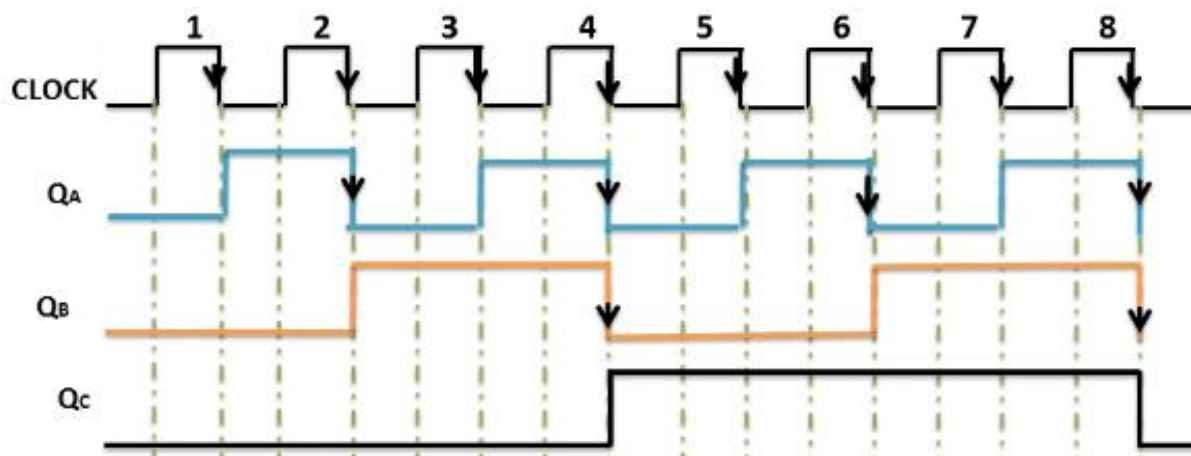
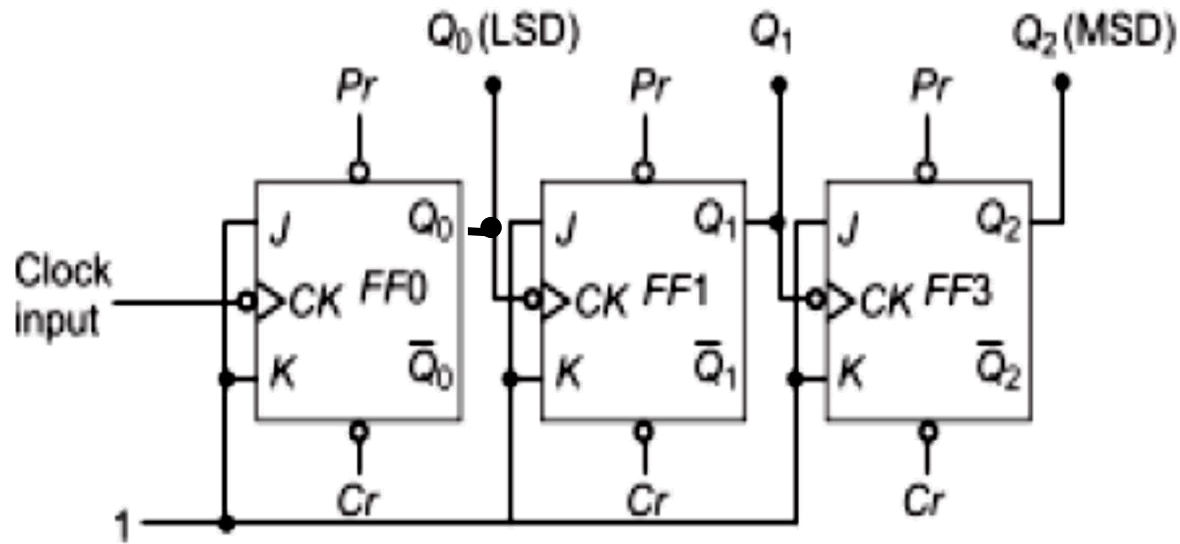
Solution

2M

Circuit

1M

Circuit 2M

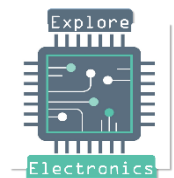


Explanation 2M

- Main clock is applied to First Bistable
- All the bistables are not clocked simultaneously
- Output of first will be the clock for second
- Similarly for next bistables

Truth Table 2M

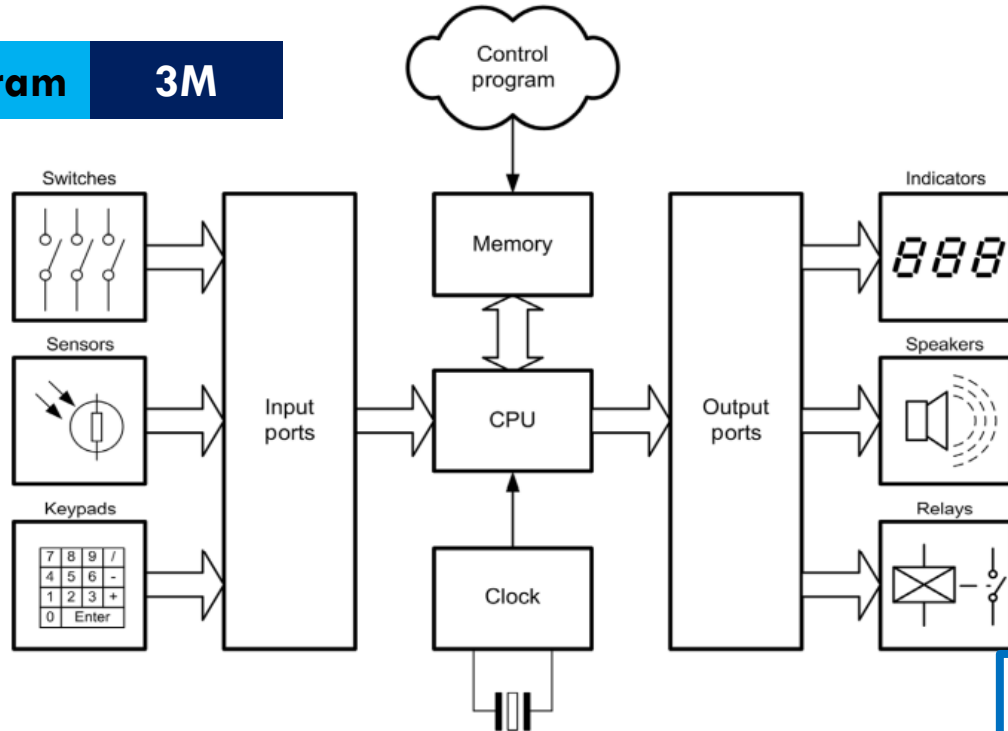
Input (Clock)	Q ₂ MS D	Q ₁	Q ₀ LSD
0	0	0	0
1	0	0	1
2	0	1	0
3	0	1	1
4	1	0	0
5	1	0	1
6	1	1	0
7	1	1	1
8	0	0	0



b With a neat block diagram show how typical input and output blocks are connected to a microcontroller unit.

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For Videos](#)

Diagram 3M



Explanation 4M

The operation of the microcontroller is controlled by a **sequence of software instructions** known as a **control program**.

The **control program** operates continuously, examining inputs from sensors, user settings and time data before making changes to the output signals sent to one or more controlled devices.

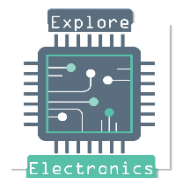
Figure 11.11 A microcontroller system with typical inputs and outputs

The **input port** signals can be derived from a number of sources, including:

- **switches** (including momentary action push-buttons)
- **sensors** (producing logic-level compatible outputs)
- **keypads** (both encoded and unencoded types)

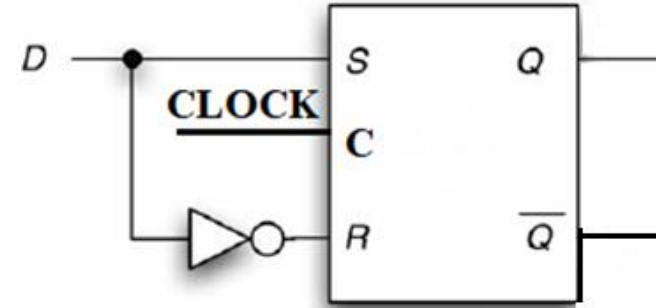
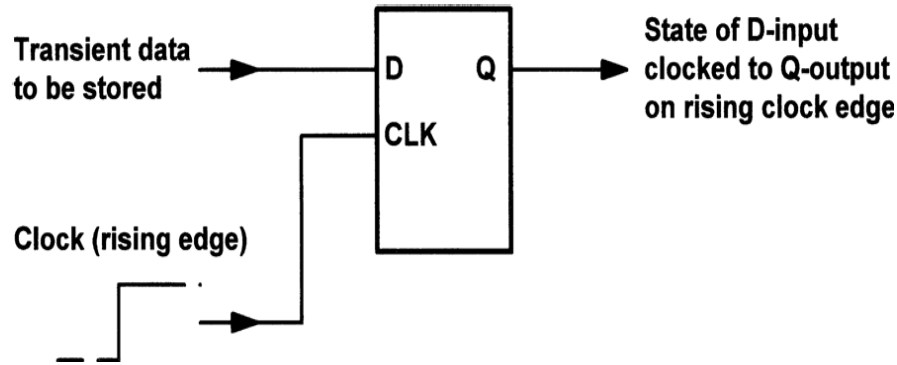
The **output port** signals can be connected to a number of devices, including

- **LED indicators** (both individual and multiple bar types)
- **LED seven-segment displays** (via a suitable interface)
- **Motors and Actuators** (both linear and rotary types) via a suitable buffer/driver or a dedicated interface
- **Relays** (both conventional electromagnetic types and optically couple solid-state types)
- Transistor drivers and other solid-state switching devices.



- The D-type bistable has two inputs: D (standing for ‘data’ or ‘delay’) and CLOCK (CLK).
- D-type bistable is a modified Set-Reset bistable with the addition of an inverter to prevent the S and R inputs from being at the same logic level.

Diagram 1M



Truth Table 2M

INPUTS		OUTPUTS		COMMENTS
CLOCK	D	Q_{N+1}	\overline{Q}_{N+1}	
0	X	Q	Q	Memory (Hold)
1	0	0	1	Reset
1	1	1	0	Set

Timing Diagram 2M

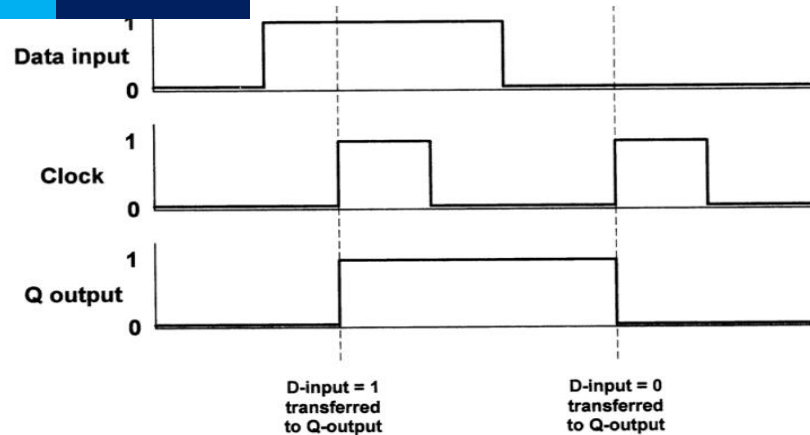
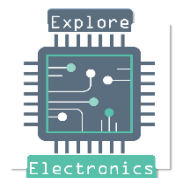


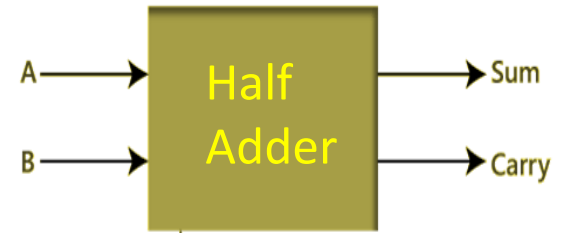
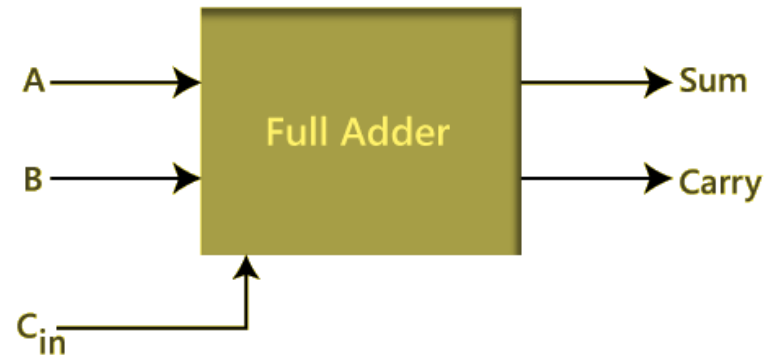
Figure 10.21 Timing diagram for the D-type bistable



Q.04 a Design a full adder using two half adders and an OR-gate.

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Diagram 1M



Half Adder 2M

Truth Table			
Input		Output	
A	B	Sum	Carry
0	0	0	0
0	1	1	0
1	0	1	0
1	1	0	1

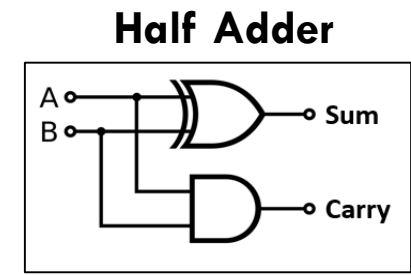
Truth Table 2M

Input			Output	
A	B	Cin	Sum	Carry
0	0	0	0	0
0	0	1	1	0
0	1	0	1	0
0	1	1	0	1
1	0	0	1	0
1	0	1	0	1
1	1	0	0	1
1	1	1	1	1

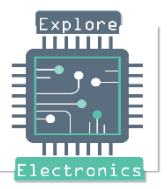
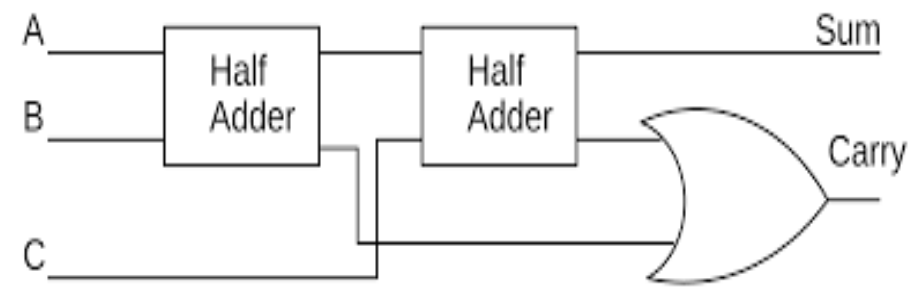
Expressions 1M

$$\text{Sum} = C_{in} \oplus (A \oplus B)$$

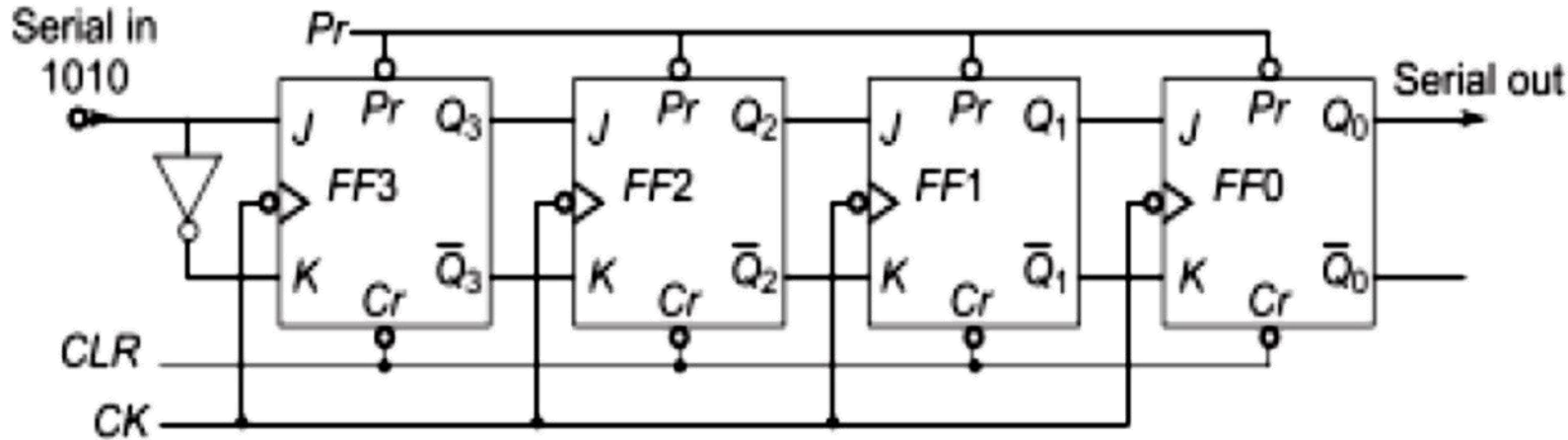
$$\text{Carry} = AB + AC_{in} + BC_{in}$$



Circuit 2M



- **Shift register** is a type of digital circuit using a cascade of flip-flops where the output of one flip-flop is connected to the input of the next.
- They share a single clock signal, which causes the data stored in the system to shift from one location to the next.



Circuit

3M

Explanation

2M

When CLR=0 all Flip-Flop output is 0
 When Pr= 0 all Flip-Flop output is 1
 When CLR=1 and Pr=1 and depends on Serial in data, Flip-Flop stores data and shift to next stage in clock cycle

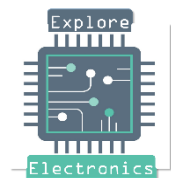
Truth Table

2M

Clock Pulse	Serial In	Q ₃	Q ₂	Q ₁	Q ₀ (Serial Out)
0	0	0	0	0	0
1	1	1	0	0	0
2	0	0	1	0	0
3	1	1	0	1	0
4	0	0	1	0	1
5	0	0	0	1	0
6	0	0	0	0	1
7	0	0	0	0	0

Data Entered

1 Register Cleared



c Write a note on different data types mentioning the bit size and range of values supported.

5

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Explanation **2M**

- Individual bits within a byte are numbered from 0 (least significant bit) to 7 (most significant bit).
- In the case of 16-bit words, the bits are numbered from 0 (least significant bit) to 15 (most significant bit).
- In Signed: most significant bit indicates the sign of the number (1 = negative, 0 = positive).

Representation **2M**

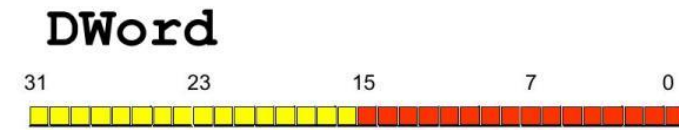
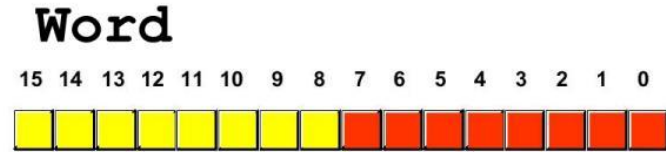
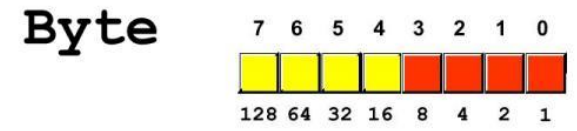
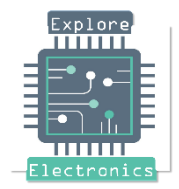


Table 11.2 Data types

Table **2M**

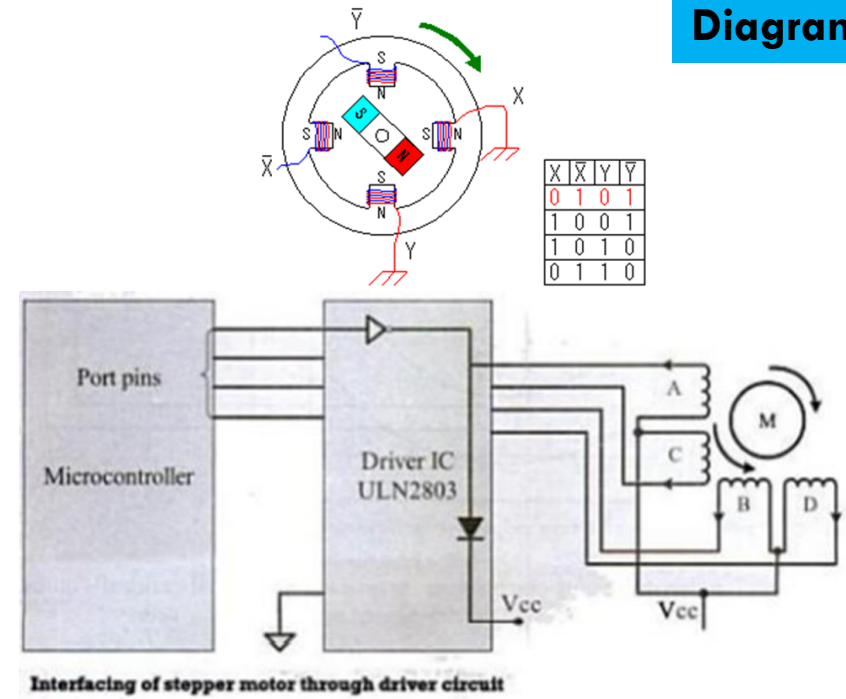
Data type	Bits	Range of values
Unsigned byte	8	0 to 255
Signed byte	8	-128 to +127
Unsigned word	16	0 to 65,535
Signed word	16	-32,768 to + 32,767



Explanation 2M

- ✓ A Stepper motor is an electro-mechanical device which generates discrete rotation in response to dc electrical signals.
- ✓ Stepper motor rotor has a permanent magnet and the stator has four electromagnetic coils which remain stationary.
- ✓ Whenever the coils energized by applying the current, the electromagnetic field is created, resulting the rotation of rotor.
- ✓ Coils should be energized in a particular sequence to make discrete rotation of the rotor.

Diagram 2M



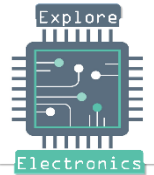
Full Step Table 2M

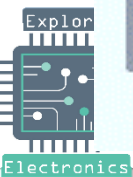
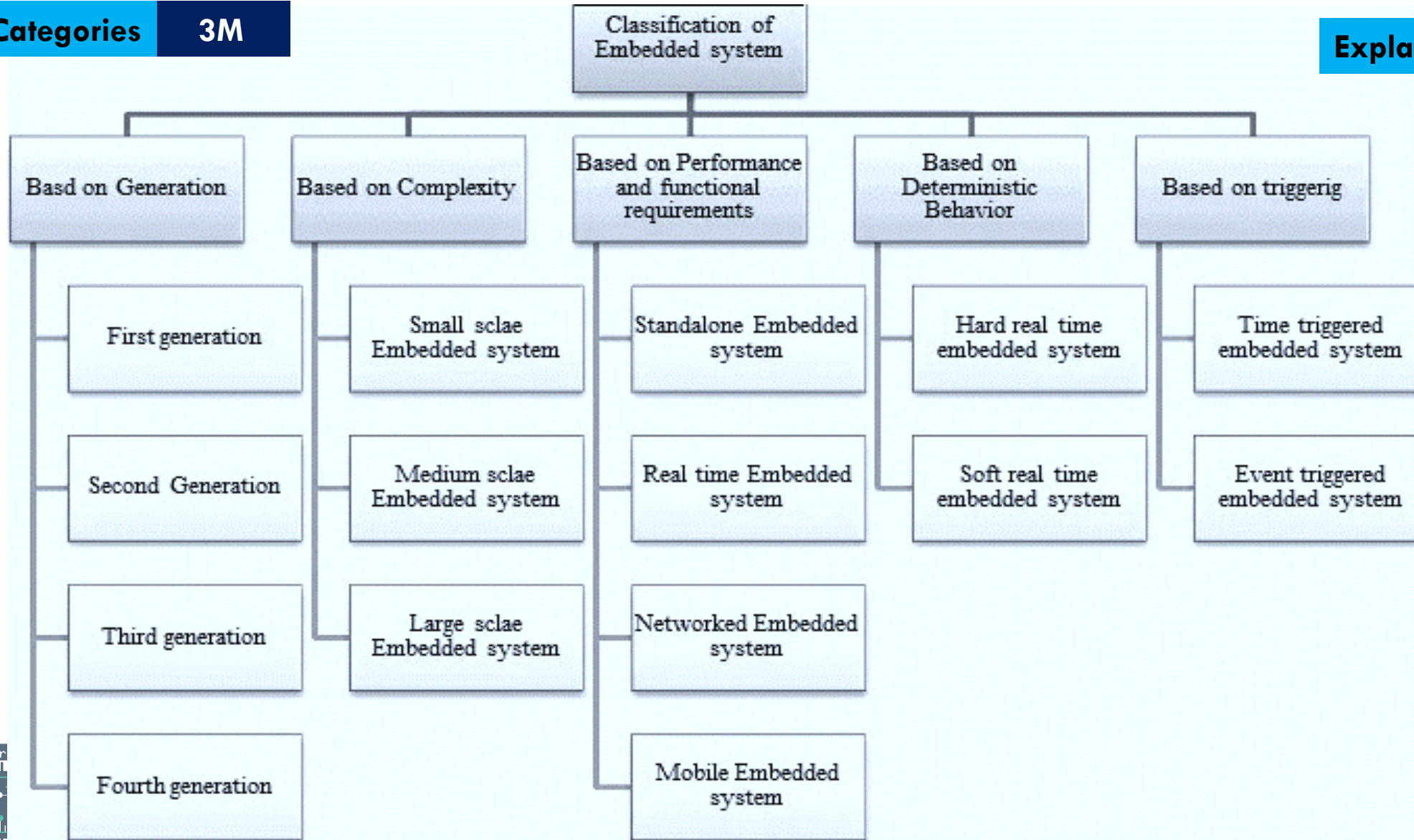
Step	Coil A	Coil B	Coil C	Coil D
1	H	H	L	L
2	L	H	H	L
3	L	L	H	H
4	H	L	L	H

Two coils are energized at a time, produces more torque. Hence, the power consumption is also high.

Applications 2M

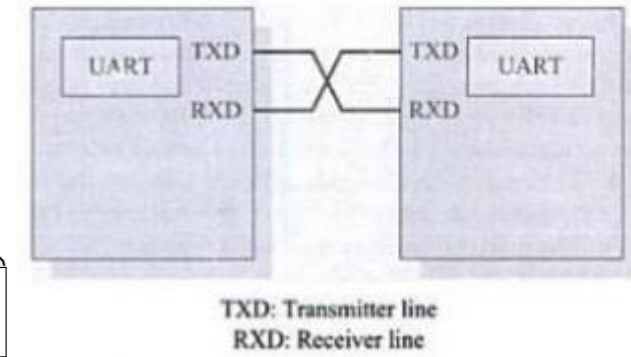
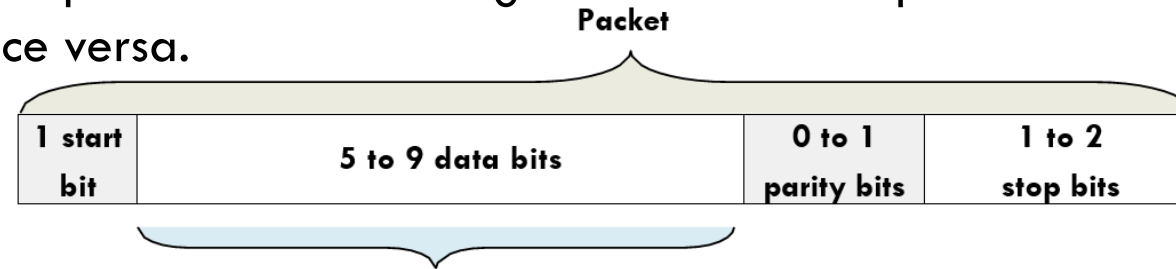
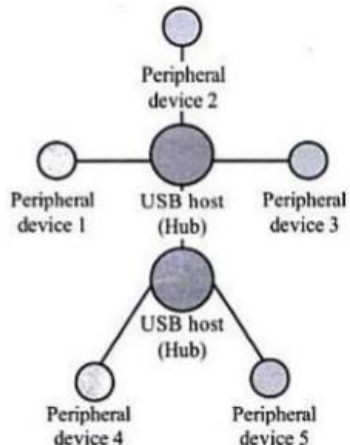
- 3D printing equipment., Textile machines.
- Printing presses., Gaming machines.
- Medical imaging machinery.
- Small robotics., CNC milling machines.
- Welding equipment.



Categories 3M**Explanation** 3M

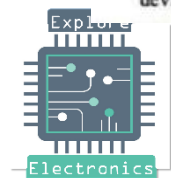
UART

- Protocol for serial data communication
- Only two wires are needed to transmit data between two UARTs.
- Data flows from the TXD pin of the transmitting UART to the RXD pin of the receiving UART and vice versa.

**USB**

Pin No.	Pin Name	Description
1	VBUS	Carries Power 5v
2	D-	Differential Data Carrier Line
3	D+	Differential Data Carrier Line
4	GND	Ground Signal Line

- ✓ The USB communication system follows a star topology with a USB host at the center and one or more USB peripheral devices.
- ✓ A USB host can support connections up to 127, including slave peripheral devices and other USB hosts.
- ✓ Each device receives unique address from the host (PC). USB transmits data in packet format. Each data packet has a standard format.

Diagram**3M****Explanation****3M**

- ✓ A loudspeaker is a transducer that converts low frequency electric current into audible sounds.
- ✓ A microphone, on the other hand, is a transducer that performs the reverse function, converting sound pressure variations into voltage or current.

- ✓ A loudspeaker is an **output transducer** designed for use in conjunction with an audio system.
- ✓ A microphone is an **input transducer** designed for use with a recording or sound reinforcing system.

- ✓ A **Active transducer** operate without any external power supply called as self generative.
- ✓ A **Passive transducer** operate with external power supply.

Explanation 3M

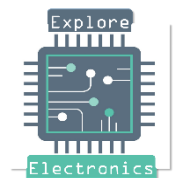
Examples 3M

Passive Transducer

- It operates under energy controlling principle.
- It require external power supply.
- The energy required for the production of the output signal is obtained from the power supply.
- E.g. Thermistors, strain gauge, LDR etc.

Active Transducer

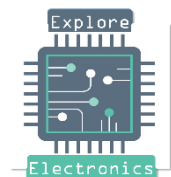
- It operates under energy conversion principle.
- Not require external power supply.
- The energy required for the production of the output signal is obtained from the physical quantity.
- E.g. Photovoltaic cell, Piezoelectric crystal etc.



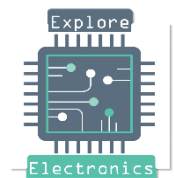
RISC	CISC
✓ Reduced Instruction Set Computer.	✓ Complex Instruction Set Computer.
✓ Software centric design.	✓ Hardware centric design.
✓ Low power consumption.	✓ High power consumption.
✓ Requires more RAM	✓ Requires a minimum amount of RAM
✓ Simple decoding of instruction.	✓ Complex decoding of instruction.
✓ Processors are highly pipelined.	✓ Processors are not pipelined or less pipelined.
✓ Execution time is very less	✓ Execution time is very high
✓ Uses multiple registers.	✓ Uses a single register.
✓ It does not require external memory for calculations	✓ It requires external memory for calculations
✓ Compound addressing mode.	✓ Limited addressing mode.
✓ RISC architecture can be used with high-end applications like telecommunication, image processing, video processing, etc.	✓ CISC architecture can be used with low-end applications like home automation, security system, consumer goods etc.
✓ Large Code Size.	✓ Small Code Size.
✓ Fixed Instruction format (32-bit)	✓ Varying formats (16 to 64 bits for each instruction).
✓ Examples: ARM, PIC, Power Architecture, Alpha,	✓ Examples: VAX, Motorola 68000 family,
✓ AVR, ARC and the SPARC.	✓ System/360, AMD and the Intel x86 CPUs.

Any 5

3M



VON NEUMANN ARCHITECTURE	HARVARD ARCHITECTURE
✓ It is ancient computer architecture based on stored program computer concept.	✓ It is modern computer architecture based model.
✓ CPU is connected data memory (RAM) and program memory (ROM) by a single memory.	✓ CPU is connected data memory (RAM) and program memory (ROM), separately.
✓ CPU cannot access instructions and data at the same time.	✓ CPU can access instructions and data at the same time.
✓ Same physical memory address is used for instructions and data.	✓ Separate physical memory address is used for instructions and data.
✓ Common bus is used for data and instruction transfer.	✓ Separate buses are used for data and instruction transfer.
✓ The speed of execution is slower. It is because it is not capable of fetching the instructions and data both at the same time.	✓ The overall speed of execution is faster. It is because the processor is capable of fetching both instructions and data at the very same time.
✓ It is cheaper in cost.	✓ It is costly.
✓ Requires less hardware, but low performance.	✓ Requires more hardware, but high performance.
✓ It is used in personal computers and small computers.	✓ It is used in microcontrollers and digital signal processing.

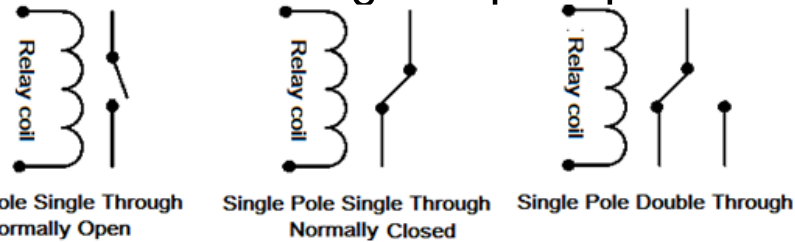


Definition 1M

- ✓ Actuator is a transducer which converts electrical signals to corresponding physical action (motion).
- ✓ Actuator acts as an output device.

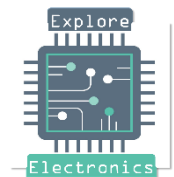
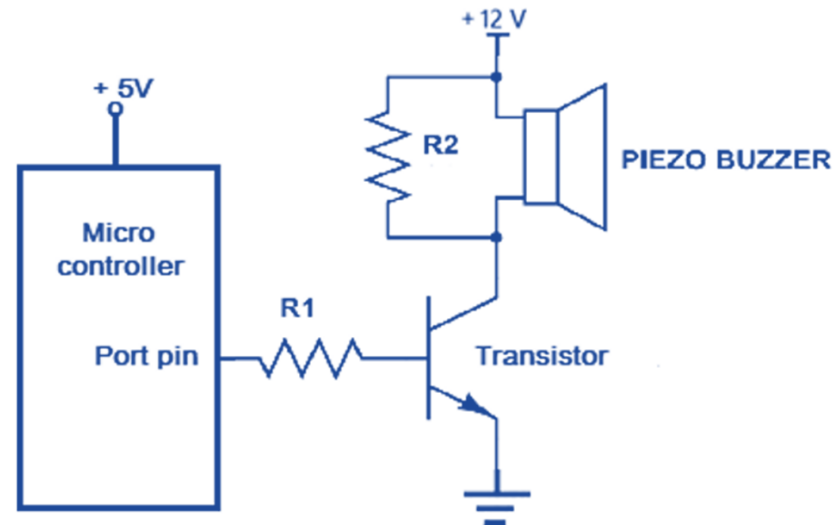
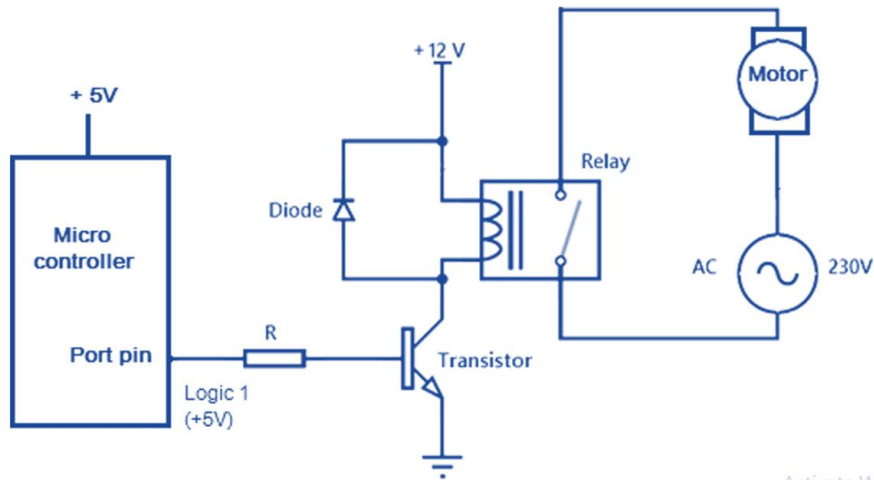
Relay 4M

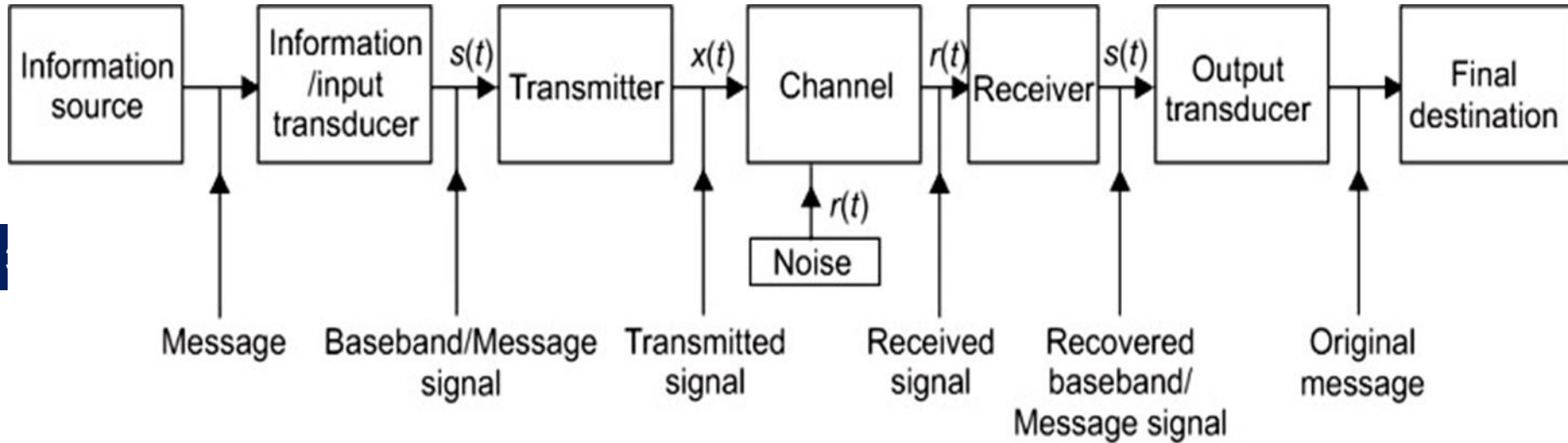
- ✓ An electro mechanical device which acts as a dynamic path selector for signals and power.
- ✓ Relay works on electromagnetic principle.



Piezo Buzzer 3M

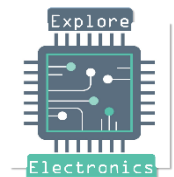
- ✓ It is a piezoelectric device for generating audio indications in embedded applications.
- ✓ A Piezo buzzer contains a piezoelectric diaphragm which produces audible sound in response to the voltage applied to it.
- ✓ Buzzer can be used as an alarm or as a fire alarm or as an intruder alarm.



**Diagram****Explanation****3M**

Write two to three lines of Explanation for these points

- ✓ Information source and transducer
- ✓ Transmitter
- ✓ Channel or medium
- ✓ Noise
- ✓ Receiver
- ✓ Output transducer and final destination



b Define the following terms: (i) Modulation (ii) Carrier communication system (iii) Baseband communication system with neat and suitable waveforms.

6

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Modulation is the process in which any **one of the parameters (amplitude, frequency or phase)** of the high frequency **carrier signal is varied** according to the instantaneous values of the low frequency message signal, **keeping other parameters constant**

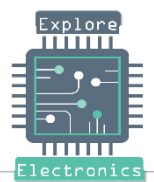
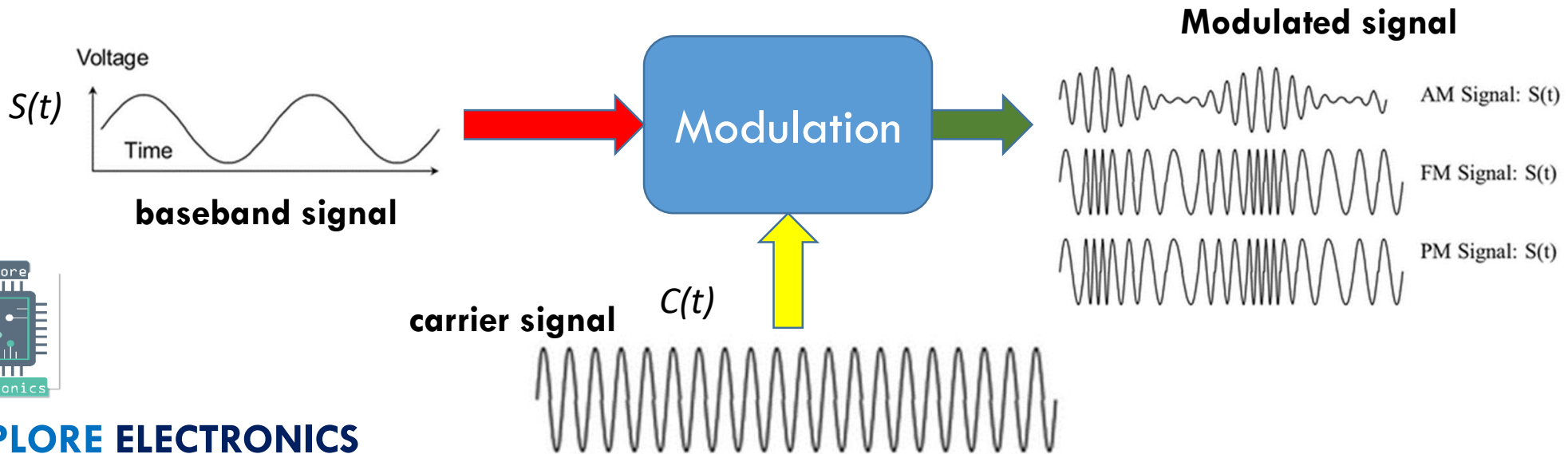
3 * 2 = 6M

Carrier Communication

- The baseband signal, which lies in the low frequency spectrum, is translated to a higher frequency spectrum
- Modulation is the main function of the transmitter.

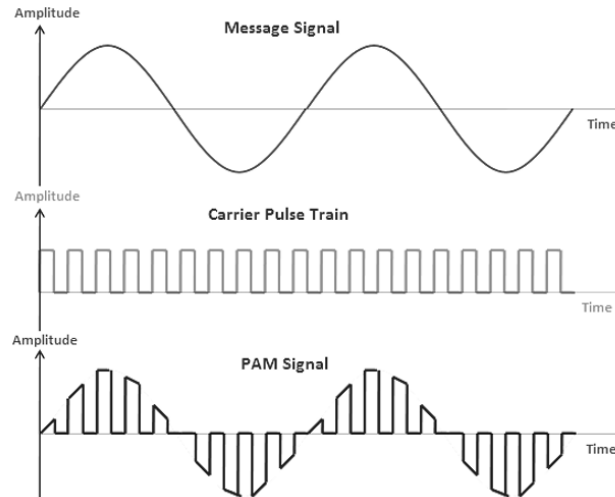
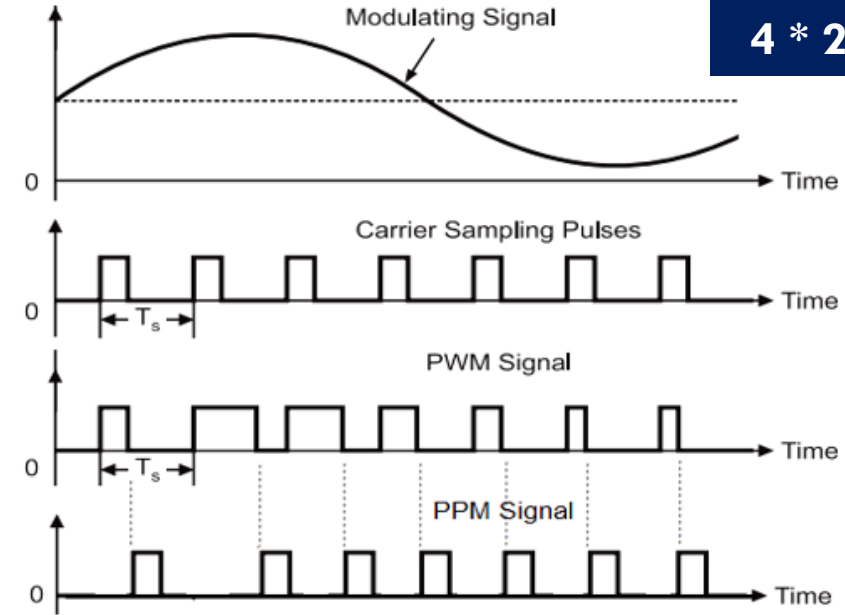
Baseband Communication

- The baseband signal is transmitted without translating it to a higher frequency spectrum
- No Modulation

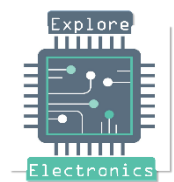


4 * 2 = 8M

S.No	Pulse Amplitude Modulation (PAM)	Pulse Duration/Width Modulation (PDM/PWM)	Pulse Position Modulation (PPM)
1	Amplitude of the pulse proportional to amplitude of modulating signal	Width of the pulse is proportional to amplitude of modulating signal	The relative position of the pulse is proportional to amplitude of modulating signal
2	Bandwidth of the transmission channel depends on the pulse width	Bandwidth of the transmission channel depends on the rise time of the pulse	Bandwidth of the transmission channel depends on the rising time of the pulse
3	Instantaneous power of the transmitter varies	Instantaneous power of the transmitter varies	Instantaneous power of the transmitter remains constant
4	Noise interference is high	Noise interference is minimum	Noise interference is minimum
5	System is complex to implement	System is simple to implement	System is simple to implement
6	Similar to amplitude modulation	Similar to frequency modulation	Similar to phase modulation



Don't Write like this.
EXPLAIN



Q. 08 a Define sampling theorem and explain when aliasing can happen. Also mention the different ways in which aliasing can be avoided.

6 [Click here For Videos](#)

Statement 1M

A band limited analog signal can be sampled and perfectly reconstructed from its samples if the sampling frequency is at least twice the maximum frequency of the base band signal.

Expressions 2M

$$\text{i.e, } f_s \geq 2f_{max}$$

Nyquist Rate: the minimum rate at which a signal can be sampled without introducing errors

$$f_s = 1/T_s \quad T_s = 1/f_s$$

Explanation 3M

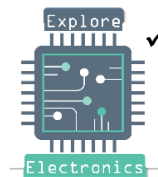
Aliasing occurred when $f_s < 2f_{max}$.

Aliasing is avoided by:

Aliasing can be avoided when $f_s > 2f_{max}$

- ✓ Applying low-pass filters or anti-aliasing filters (AAF) to the input signal before sampling and when converting a signal from a higher to a lower sampling rate.

Sampling the signal at a higher rate than the Nyquist rate ($f_s \geq 2f_{max}$).



b Define the following terms: Multipath, Constructive and destructive interference, Coherence time, Coherence bandwidth, Delay spread

10

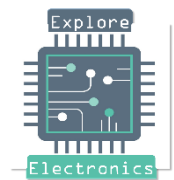
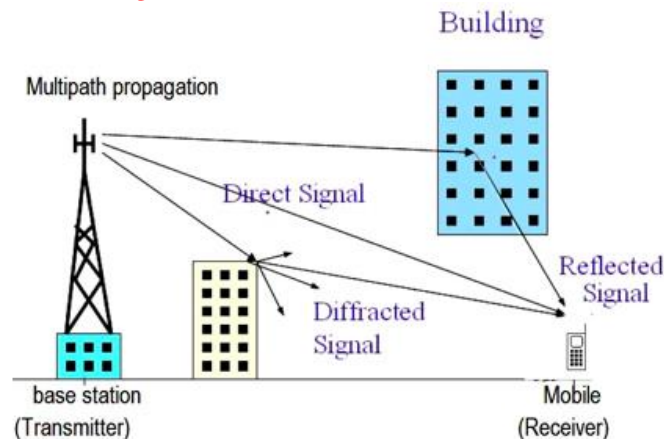
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Definitions +
1 or 2 line
explanation

2M each

- ✓ As a result of reflections and diffractions the signals can take several different paths from the transmitter to the receiver. This phenomenon is known as *multipath*.
- ✓ At the receiver end, the incoming rays can add together in different ways, which are classified as *constructive interference* and *destructive interference*.
- ✓ If the peaks of the incoming rays coincide, then they reinforce each other, a situation known as *constructive interference*.

- ✓ If the peaks of one ray coincide with the troughs of another, the result is *destructive interference*, in which the rays cancel.
- ✓ Destructive interference can make the received signal power drop to a very low level, a situation known as *fading*.



If the mobile moves from one place to another, then the ray geometry changes, so the interference pattern changes between constructive and destructive. Fading is therefore a function of time.

The amplitude and phase of the received signal vary over a time scale called the coherence time, T_c that can be estimated as

$$T_c = \frac{1}{f_D}$$

Where, f_D is mobile Doppler frequency, given by

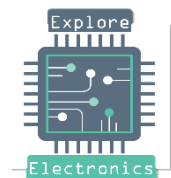
$$f_D = \frac{v}{c} f_c$$

Where, f_c is carrier frequency, v is speed of mobile and c is speed of light ($3 \times 10^8 \text{ m/s}$)

If the carrier frequency changes, wavelength of the radio signal also changes. This makes the pattern change between constructive and destructive interference. The amplitude and phase of the received signal vary over a scale called the coherence bandwidth, B_c that can be estimated as

$$B_c = \frac{1}{r}$$

Where, r is delay spread of radio channel.



Antenna is a device used for converting electromagnetic radiation in space into electrical currents in conductors or vice-versa, depending on whether it is being used for receiving or for transmitting, respectively

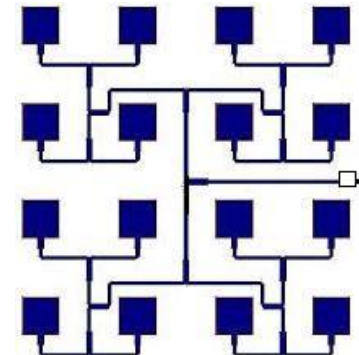
Definition 1M

Types of Antenna

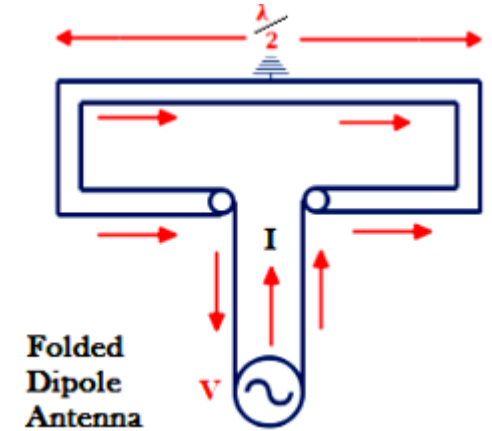
- Omni-directional Antennas
- Dipole Antennas
- Collinear omni Antennas
- Directional Antennas
- Patch Antennas
- Patch Array Antennas
- Yagi Antennas



Omni-directional Antenna

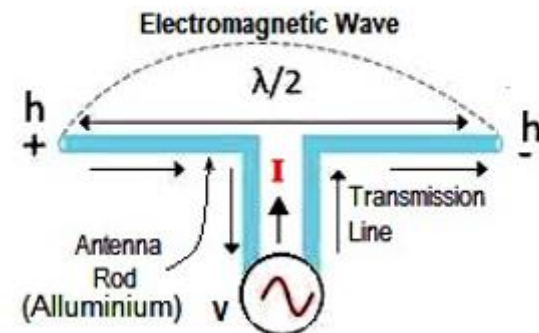


Patch array antenna



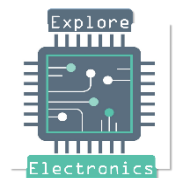
Folded Dipole Antenna

Dipole Antenna



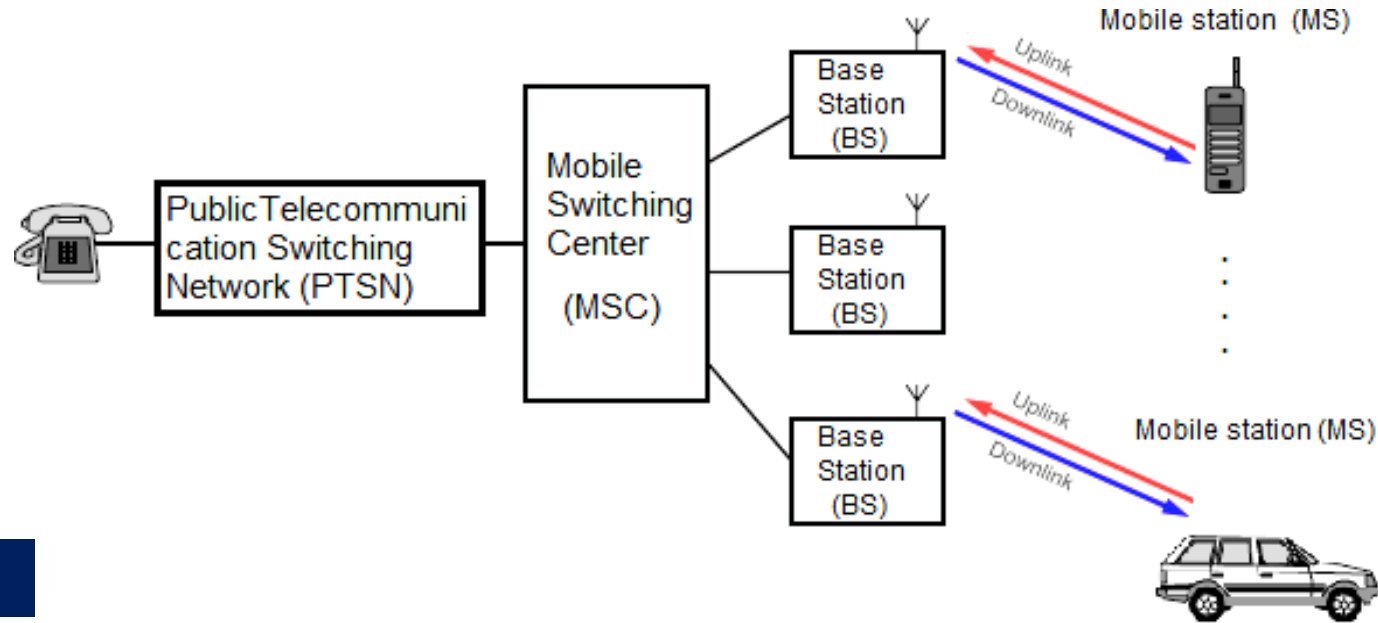
**Types
+ 1 or 2 lines
explanation**

3M



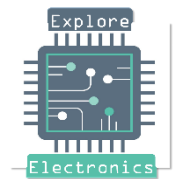
Diagram

3M



Explanation

3M



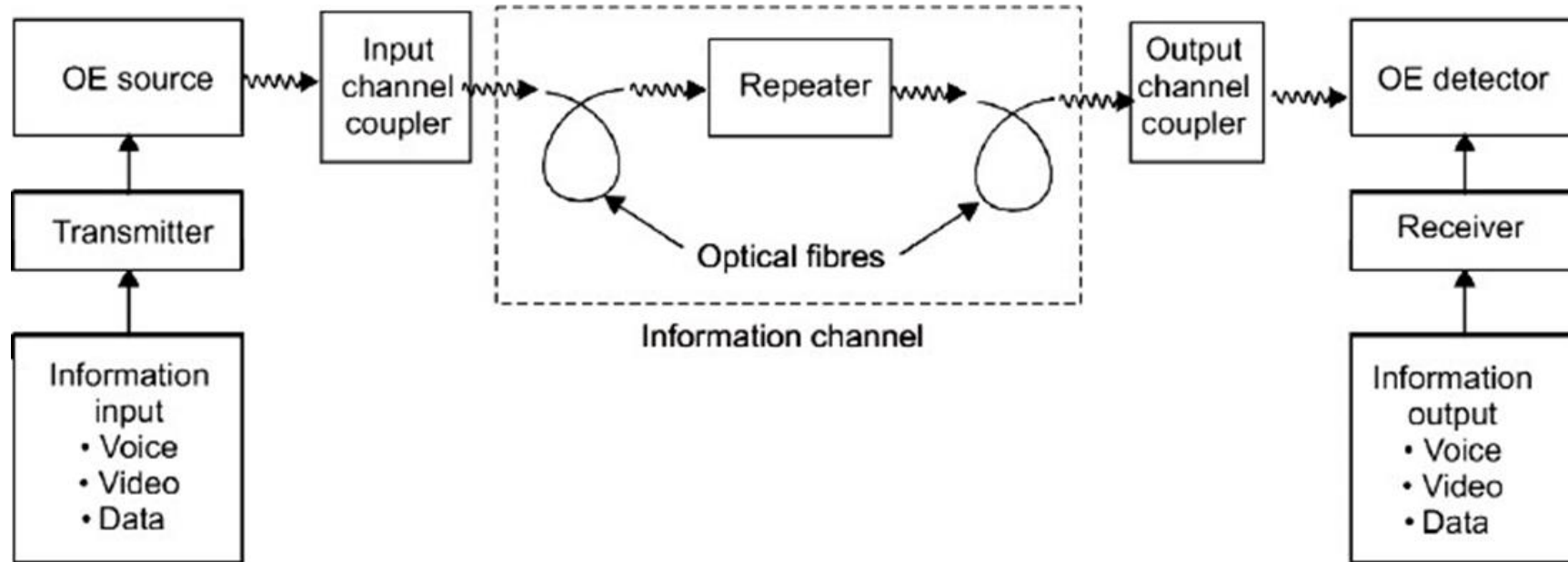


Diagram 3M

Explanation 3M

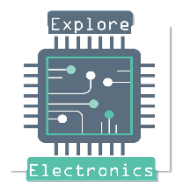
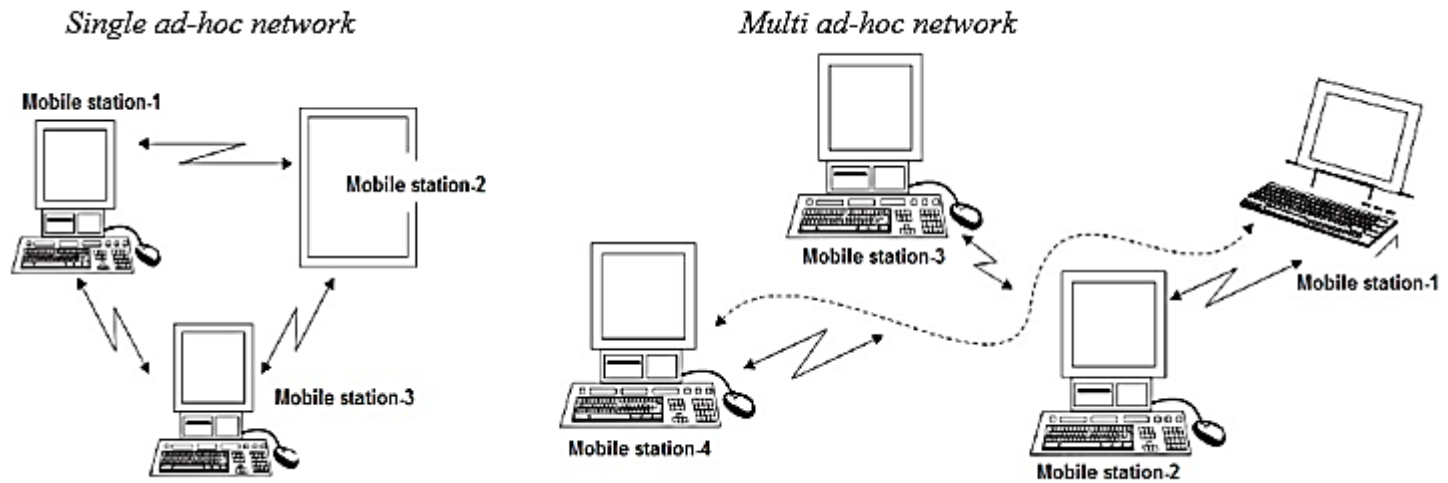


Diagram 2M + 2M



Explanation 4M

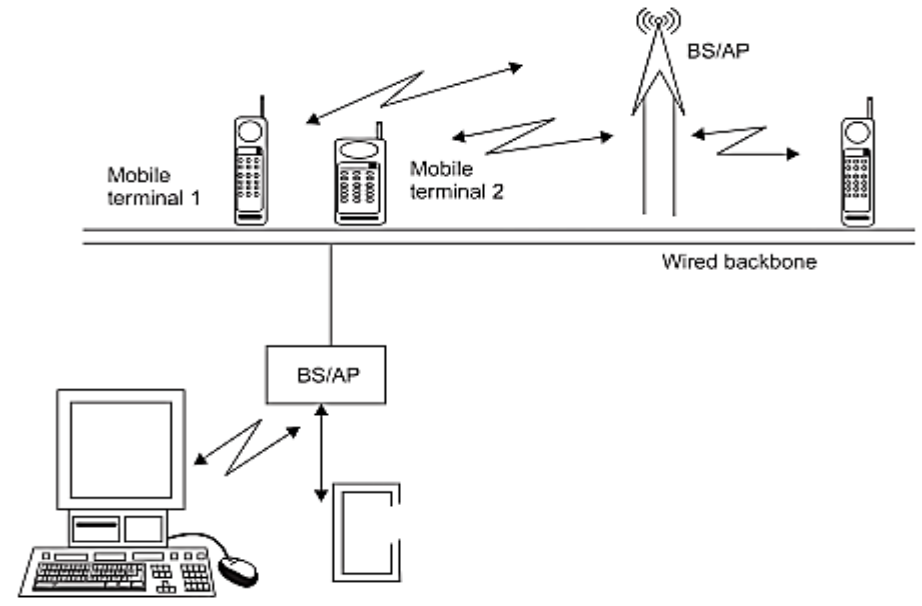
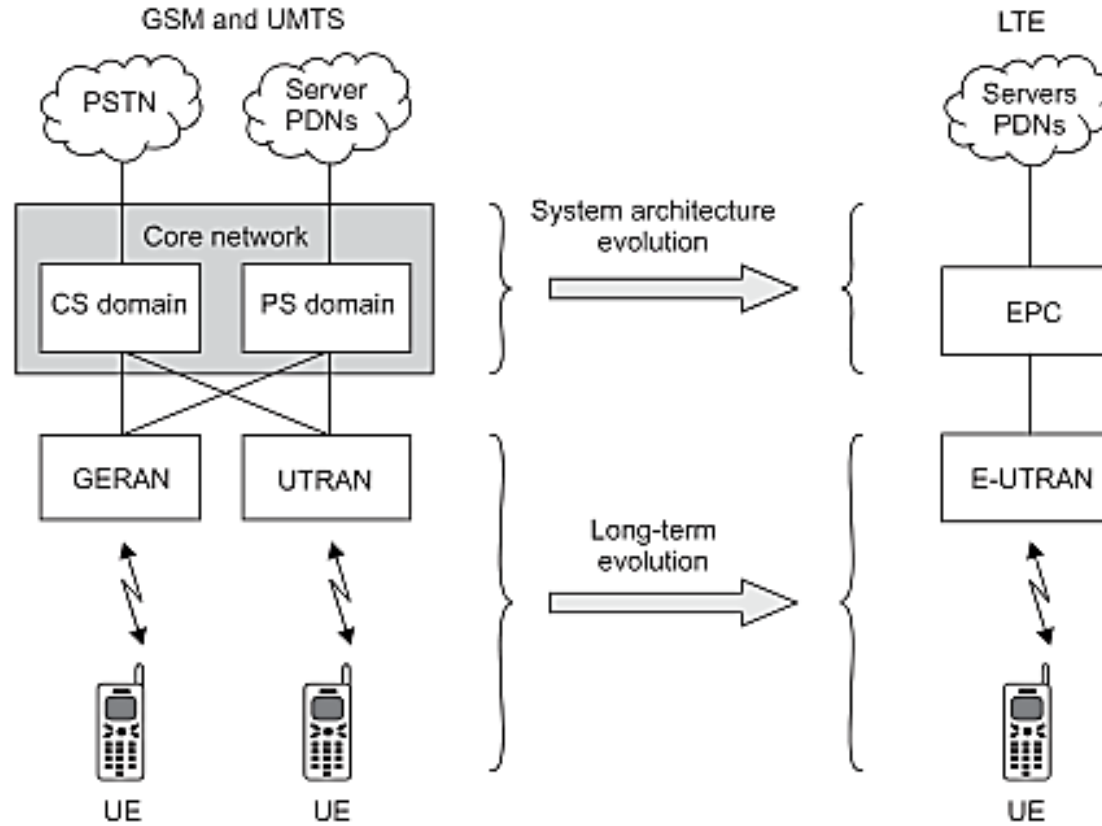


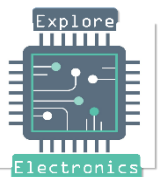
Diagram 2M + 2M



Explanation 4M

Fig. 8.14 Evolution of the system architecture from GSM and UMTS to LTE

UMTS (universal Mobile Telecommunication Services) is the main technology responsible behind 3G. *Universal Terrestrial Radio Access Network (UTRAN)* consists of multiple *Radio Network Sub-systems (RNSs)* which is equivalent to the *base station subsystem (BSS)*. RNS consists of radio transceivers referred to as Node B which are equivalent to the BTSs in the GSM architecture.

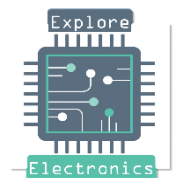


4 points + Explanation

4M

The high level requirements for a 4G technology were identified as:

- i) High spectral efficiency
- ii) Reduced cost per bit
- iii) Increased services by increasing the efficiency
- iv) Open interfaces
- v) Power efficiency
- vi) Flexible usage of frequency bands



c Draw the block diagram showing the basic elements of a satellite communication system and briefly explain them.

8

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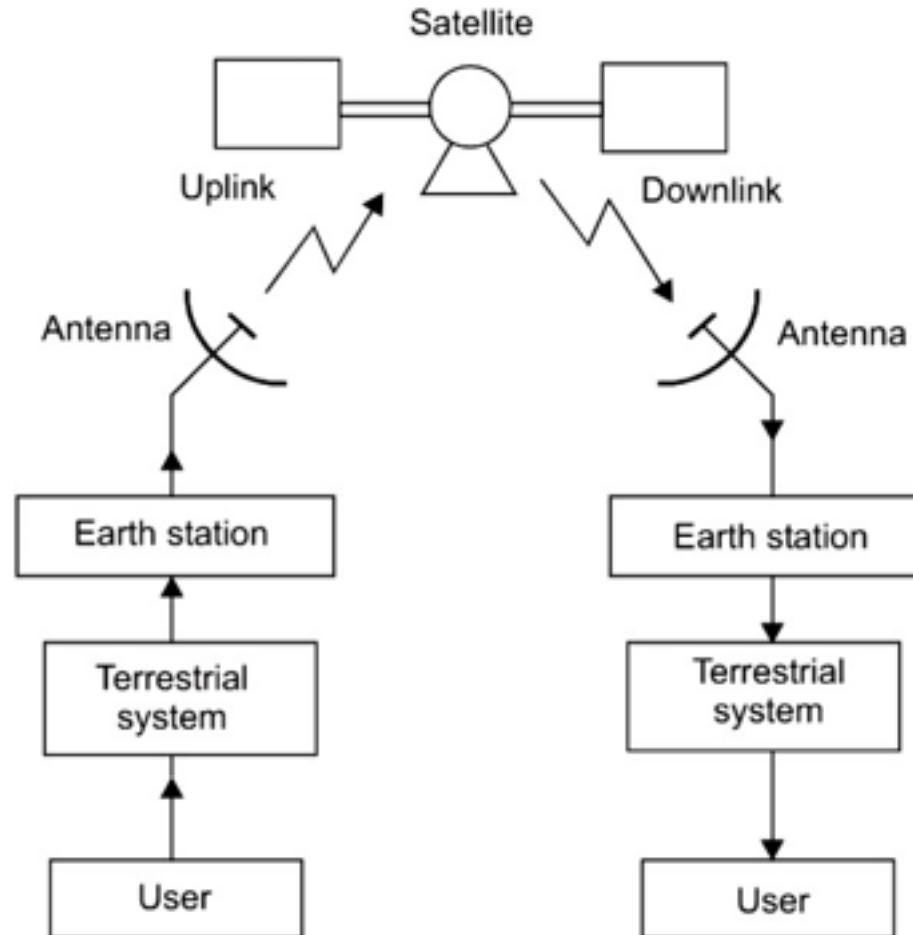
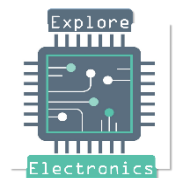
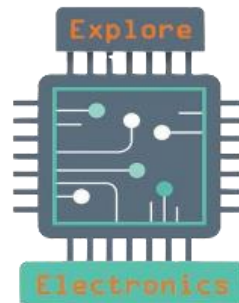


Diagram 3M

Explanation 5M



THANK YOU



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